

EAST [databases: US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM\_TDB]

(inventor)

L1	430	MIYAZAKI, KUNIO
L2	34	KAWANO, TOMOYUKI
L3	44	TOKUNAGA, KAZUYA
L4	65	IKENAGA, ICHIRO

(class/subclass)

L5	393	367/96.CCLS.
L6	332	342/61.CCLS.
L7	571	414/281.ccls.
L8	395	52/29.ccls.
L9	362	211/151.ccls.
L10	172	211/1.51.ccls.
L11	149	211/1.57.ccls.
L12	1017	180/167.ccls.

(text)

L14	17	(moveable or movable) with (partition or shelf\$4 or wall or rack) (motor or drive) with control\$4 distance with sens\$5
L13	12	L1 AND L2 AND L3 AND L4
L16	0	CONTROL METHOD FOR MOVING RACKS
L17	39	CONTROL METHOD MOVING RACKS
L18	2482	CONTROL MOVING RACKS

(forward/backward ids)

L15	19	( ("20020131849" "20040035060" "20040187395" "20040226256" "4039040" "5333983" "5842585" "6845834" "7032762").PN.
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(interference)

L19	740	((moveable or movable) and (partition or shelf\$4 or wall or rack) and (motor or drive) and control\$4 and distance and sens\$5).clm.
L20	392	((moveable or movable) and (partition or shelf\$4 or wall or rack) and (motor or drive) and control\$4 and predetermined and distance and sens\$5).clm.
L21	94	((moveable or movable) and (partition or shelf\$4 or wall or rack) and (motor or drive) and input and control\$4 and predetermined and distance and sens\$5).clm.
L22	64	((moveable or movable) and (partition or shelf\$4 or wall or rack) and (motor or drive) and input and control\$4 and maintain\$4 and predetermined and distance and sens\$5).clm.